

# **Intro to Software Testing**

## **Chapter 7.2**

# **Graph Coverage Criteria Overview**

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SWE 437

Adapted from slides by Paul Ammann & Jeff Offutt

# Testing and Covering Graphs (7.2)

We use graphs in testing as follows:

- Develop a model of the software as a graph
- Require tests to visit or tour specific sets of nodes, edges, or subpaths

**Test requirements (TR):** Describe properties of test paths

**Test Criterion:** Rules that define test requirements

**Satisfaction:** Given a set  $TR$  of test requirements for a criterion  $C$ , a set of tests  $T$  satisfies  $C$  on a graph if and only if for every test requirement in  $TR$ , there is a test path in  $path(T)$  that meets the test requirement  $tr$ .

**Structural Coverage Criteria:** Defined on a graph just in terms of nodes and edges

# Node and Edge Coverage

The first (and simplest) two criteria require that each node and edge in a graph be executed.

**Node Coverage (NC) : Test set  $T$  satisfies node coverage on graph  $G$  iff for every syntactically reachable node  $n$  in  $N$ , there is some path  $p$  in  $path(T)$  such that  $p$  visits  $n$ .**

This statement is a bit cumbersome, so we abbreviate it in terms of the set of test requirements.

**Node Coverage (NC) : TR contains each reachable node in  $G$ .**

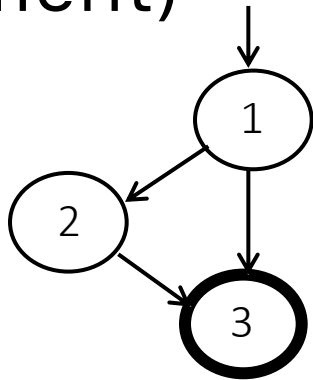
# Node and Edge Coverage

Edge coverage is slightly stronger than node coverage

**Edge Coverage (EC) : TR contains each reachable path of length up to 1, inclusive, in G**

The phrase "*length up to 1*" allows for graphs with one node and no edges

NC and EC are only different when there is an edge and another subpath between a pair of nodes (as in an "if-else" statement)

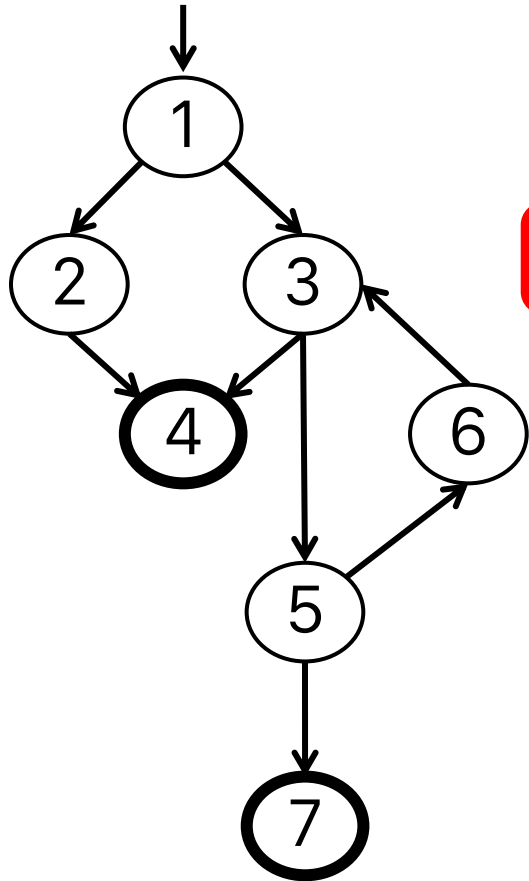


Node Coverage : ? TR = { 1, 2, 3 }  
Test Path = [ 1, 2, 3 ]

Edge Coverage : ? TR = { (1, 2), (1, 3), (2, 3) }  
Test Paths = [ 1, 2, 3 ]  
[ 1, 3 ]

# In-class group exercise

## Graph criteria EC

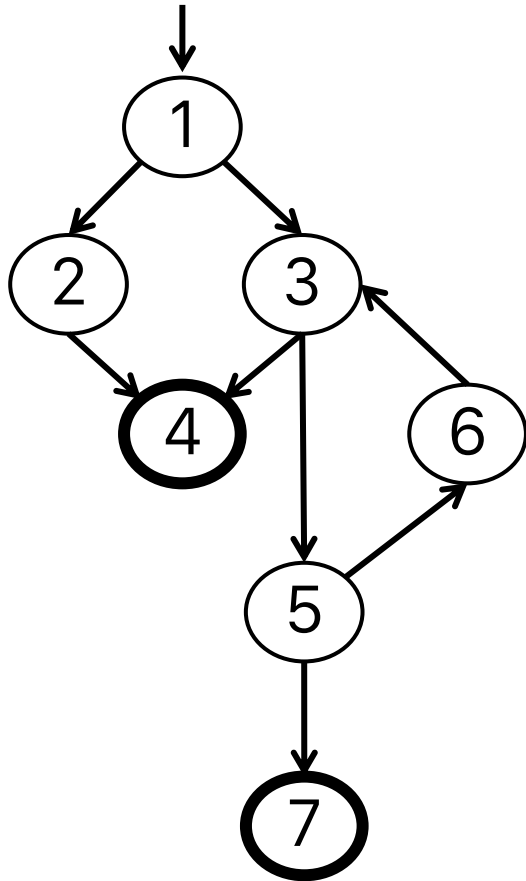


Answer the following questions for the graph on the left

1. List test paths that satisfy edge coverage.
2. Write the set of test requirements for edge-pair coverage.
3. List test paths that satisfy edge-pair coverage.
4. Write the set of test requirements for prime path coverage.
5. List test paths that satisfy prime path coverage.

# In-class group exercise

## Graph criteria EC



Answer the following questions for the graph on the left

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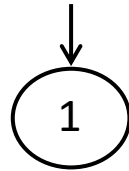
[1, 2, 4]

[1, 3, 5, 6, 3, 4]

[1, 3, 5, 7]

# Node and Edge Coverage

A graph with **only one node** will not have any edges

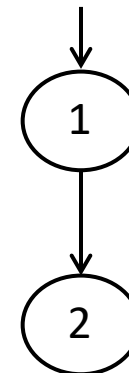


It may seem trivial, but formally, Edge Coverage needs to require Node Coverage on this graph

Otherwise, Edge Coverage will not subsume Node Coverage

- So we define "**length up to 1**" instead of simply "length 1"

We have the same issue with graphs that have only **one edge** – for Edge-Pair Coverage...

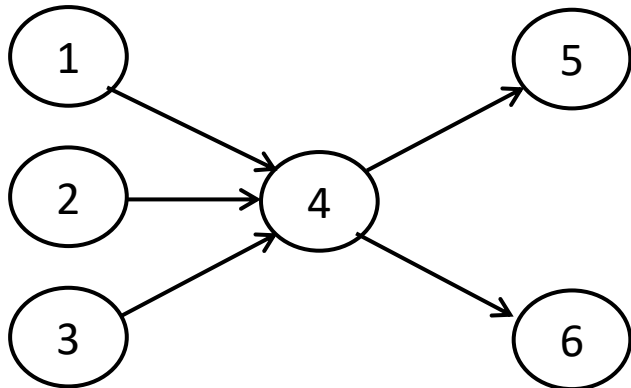


# Covering Multiple Edges

Edge-pair coverage requires **pairs of edges**, or subpaths of length 2

**Edge-Pair Coverage (EPC) : TR contains each reachable path of length up to 2, inclusive, in G**

The phrase "**length up to 2**" is used to include graphs that have less than 2 edges



Edge-Pair Coverage : ?

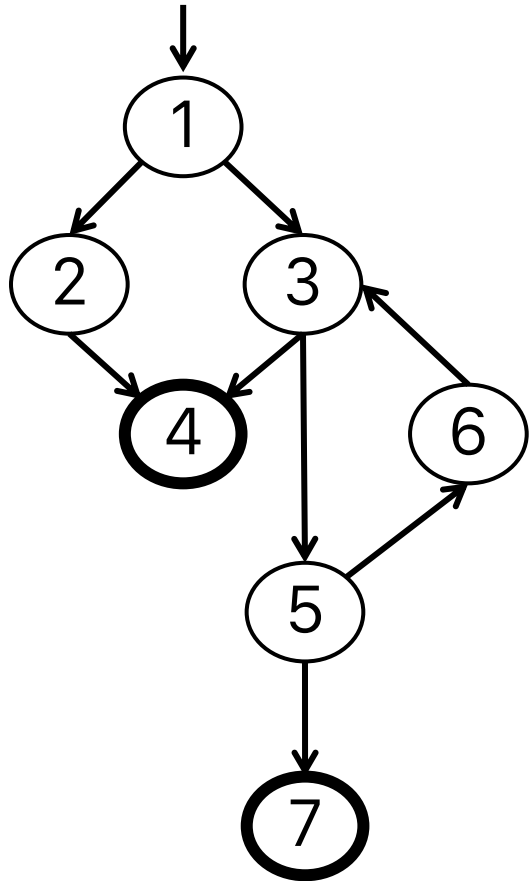
TR = { [1,4,5], [1,4,6], [2,4,5], [2,4,6], [3,4,5], [3,4,6] }

The logical extension is to require **all paths...**



# In-class group exercise

## Graph criteria EPC

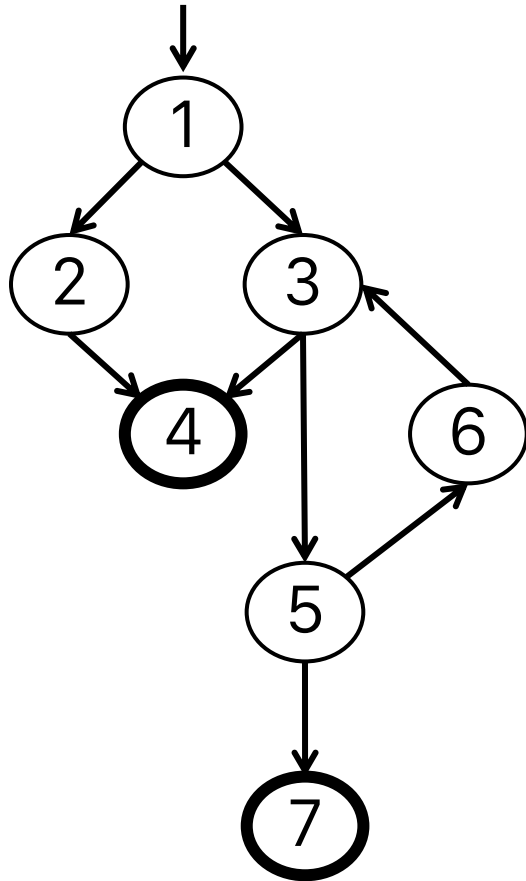


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# In-class group exercise

## Graph criteria EPC



Answer the following questions for the graph on the left

1. List test paths that satisfy edge coverage.
2. Write the set of test requirements for edge-pair coverage.
3. List test paths that satisfy edge-pair coverage.

TR = {[1, 2, 4], [1, 3, 4], [1, 3, 5], [3, 5, 6], [5, 6, 3], [6, 3, 4], [6, 3, 5], [3, 5, 7]}

Test paths = [1, 2, 4]; [1, 3, 4]; [1, 3, 5, 6, 3, 4]; [1, 3, 5, 6, 3, 5, 7]

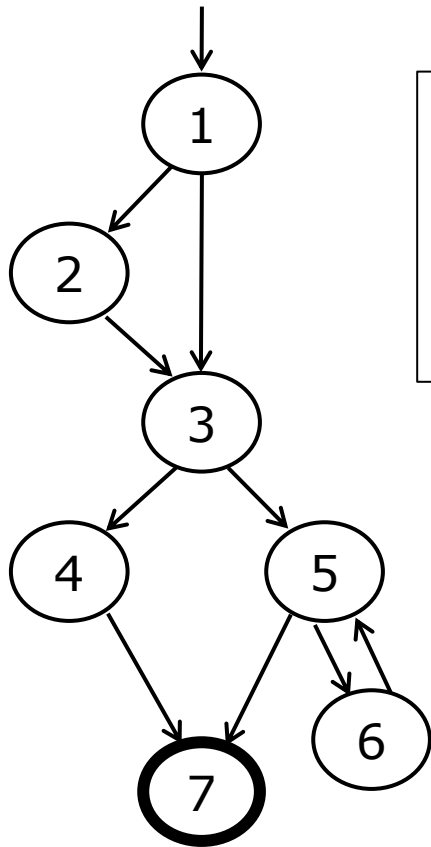
# Covering Multiple Edges

Complete Path Coverage (CPC): TR contains all paths in G.

Unfortunately, this is **impossible** if the graph has a loop, so a weak compromise make the tester decide which paths:

Specified Path Coverage (SPC): TR contains a set  $S$  of test paths, where  $S$  is supplied as a parameter.

# Covering Multiple Edges



*Write down  
the TRs and  
Test Paths  
for these  
criteria*

## Node Coverage

TR = { 1, 2, 3, 4, 5, 6, 7 }

Test Paths: [ 1, 2, 3, 4, 7 ] [ 1, 2, 3, 5, 6, 5, 7 ]

## Edge Coverage

TR = { (1,2), (1,3), (2,3), (3,4), (3,5), (4,7), (5,6), (5,7), (6,5) }

Test Paths: [ 1, 2, 3, 4, 7 ] [ 1, 3, 5, 6, 5, 7 ]

## Edge-Pair Coverage

TR = { [1,2,3], [1,3,4], [1,3,5], [2,3,4], [2,3,5], [3,4,7],  
[3,5,6], [3,5,7], [5,6,5], [6,5,6], [6,5,7] }

Test Paths: [ 1, 2, 3, 4, 7 ] [ 1, 2, 3, 5, 7 ] [ 1, 3, 4, 7 ]  
[ 1, 3, 5, 6, 5, 6, 5, 7 ]

## Complete Path Coverage

Test Paths: [ 1, 2, 3, 4, 7 ] [ 1, 2, 3, 5, 7 ] [ 1, 2, 3, 5, 6, 5, 7 ]  
[ 1, 2, 3, 5, 6, 5, 6, 5, 7 ] [ 1, 2, 3, 5, 6, 5, 6, 5, 6, 5, 7 ] ...

# Handling Loops in Graphs

If a graph contains a loop, it has an **infinite** number of paths

Thus CPC is **not feasible**

SPC is not satisfactory because the results are **subjective** and vary with the tester

Attempts to "deal with" **loops**:

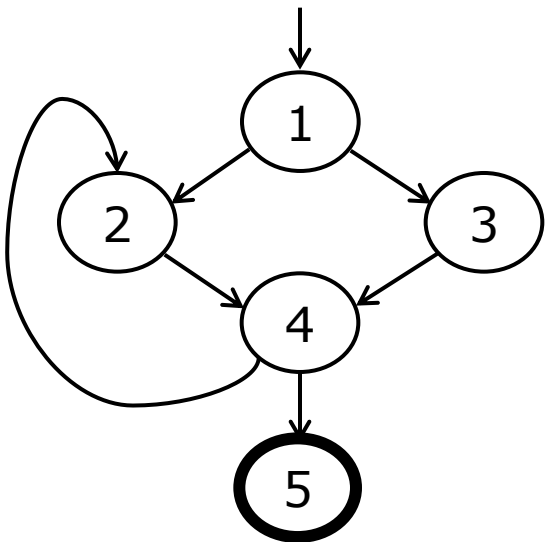
- **1970s**: Execute cycles once
- **1980s**: Execute each loop, exactly once
- **1990s**: Execute loops 0 times, once, more than once
- **2000s**: Prime paths (touring, sidetrips, detours)

# Simple Paths and Prime Paths

**Simple path:** A path from node  $n_i$  to  $n_j$  is simple if no node appears more than once, except possibly the first and last nodes are the same

- No internal loops
- A loop is a simple path

**Prime path:** A simple path that does not appear as a proper subpath of any other simple path



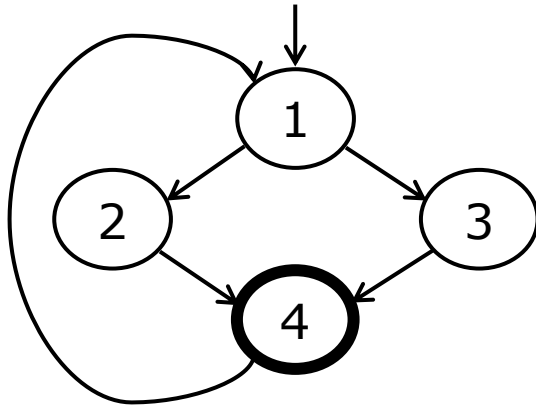
Write down the simple and prime paths for this graph

**Simple Paths** : [1,2,4,5], [1,3,4,2], [1,3,4,5], [1,2,4], [1,3,4], [2,4,2], [2,4,5], [3,4,2], [3,4,5], [4,2,4], [1,2], [1,3], [2,4], [3,4], [4,2], [4,5], [1], [2], [3], [4], [5]

**Prime Paths** : [1,2,4,5], [1,3,4,2], [1,3,4,5], [2,4,2], [4,2,4]

# Simple Paths and Prime Paths

What if we change the graph?



*Write down the simple and prime paths for this graph*

**Simple Paths** : [1,2,4,1], [1,3,4,1], [2,4,1,2], [2,4,1,3], [3,4,1,2], [3,4,1,3], [4,1,2,4], [4,1,3,4], [1,2,4], [1,3,4], [2,4,1], [3,4,1], [4,1,2], [4,1,3], [1,2], [1,3], [2,4], [3,4], [4,1], [1], [2], [3], [4]

**Prime Paths** : [1,2,4,1], [1,3,4,1], [2,4,1,2], [2,4,1,3], [3,4,1,2], [3,4,1,3], [4,1,2,4], [4,1,3,4]

# Prime Path Coverage

A simple, elegant and finite criterion that requires **loops** to be executed as well as skipped

**Prime Path Coverage (PPC): TR contains each prime path in G.**

Will tour all paths of length 0, 1,...

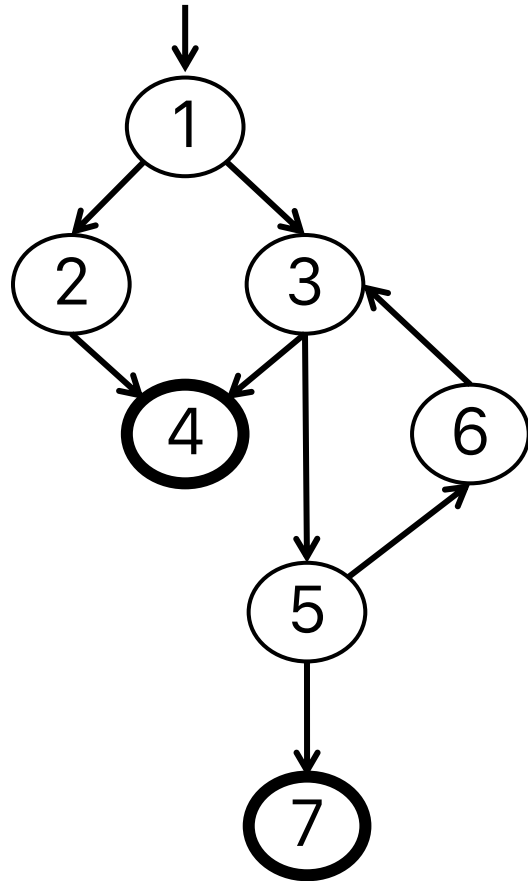
That is, it **subsumes** node and edge coverage

PPC almost, but **not quite**, subsumes **EPC**...



# In-class group exercise

## Graph criteria PPC

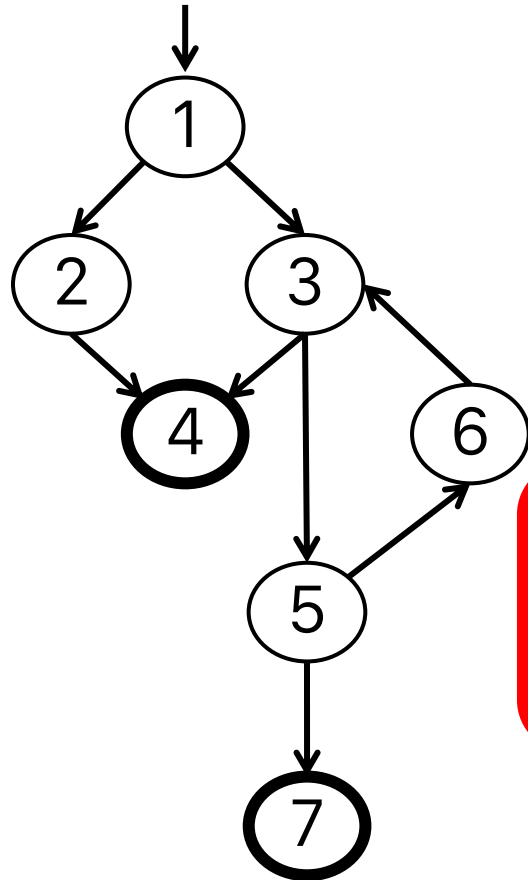


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TR = {[1, 2, 4], [1, 3, 4], [1, 3, 5, 7], [3, 5, 6, 3], [6, 3, 5, 6], [5, 6, 3, 5], [1, 3, 5, 6], [6, 3, 5, 7]}

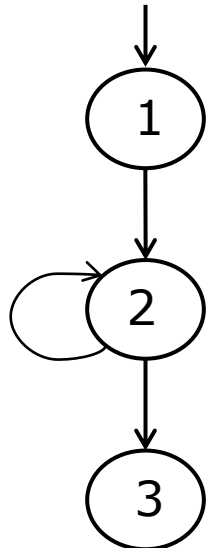
Test paths = [1, 2, 4], [1, 3, 4], [1, 3, 5, 7], [1, 3, 5, 6, 3, 5, 6, 3, 5, 7]

# PPC Does Not Subsume EPC

If a node has an edge to itself (*self edge*), **EPC** requires **[n, n, m]** and **[m, n, n]**

**[n, n, m]** is not prime

Neither **[n, n, m]** nor **[m, n, n]** are simple paths (not prime)



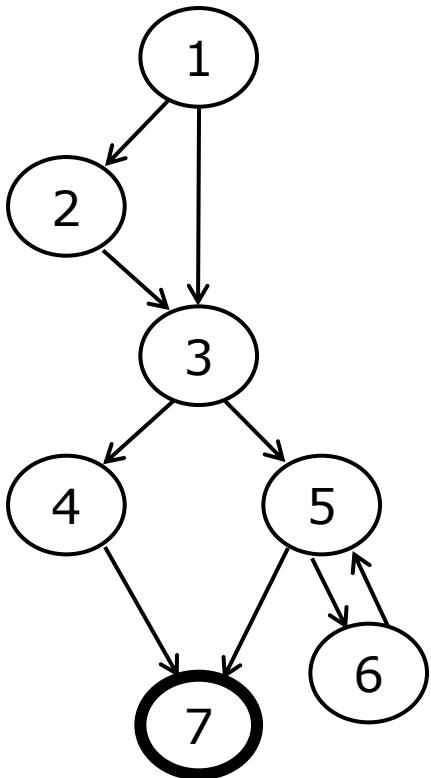
EPC Requirements : ?  
TR = { [1,2,3], [1,2,2], [2,2,3], [2,2,2] }

PPC Requirements : ?  
TR = { [1,2,3], [2,2] }

# Prime Path Example

The previous example has 38 **simple** paths

Only **nine** *prime paths*



Write down all  
9 prime paths

## Prime Paths

[1, 2, 3, 4, 7]  
[1, 2, 3, 5, 7]  
[1, 2, 3, 5, 6]  
[1, 3, 4, 7]  
[1, 3, 5, 7]  
[1, 3, 5, 6]  
[6, 5, 7]  
[6, 5, 6]  
[5, 6, 5]

Execute loop 0  
times

Execute loop  
once

Execute loop more  
than once

# Touring, Sidetrips, and Detours

Prime paths do not have **internal loops** ... test paths might

**Tour:** *A test path  $p$  tours subpath  $q$  if  $q$  is a subpath of  $p$*

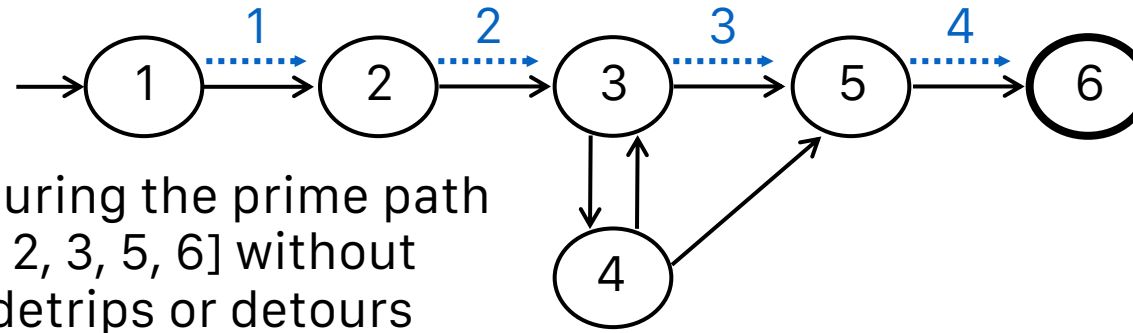
**Tour with sidetrips:** *A test path  $p$  tours subpath  $q$  with sidetrips iff every edge in  $q$  is also in  $p$  in the same order*

- The tour can include a sidetrip, as long as it comes back to the same node

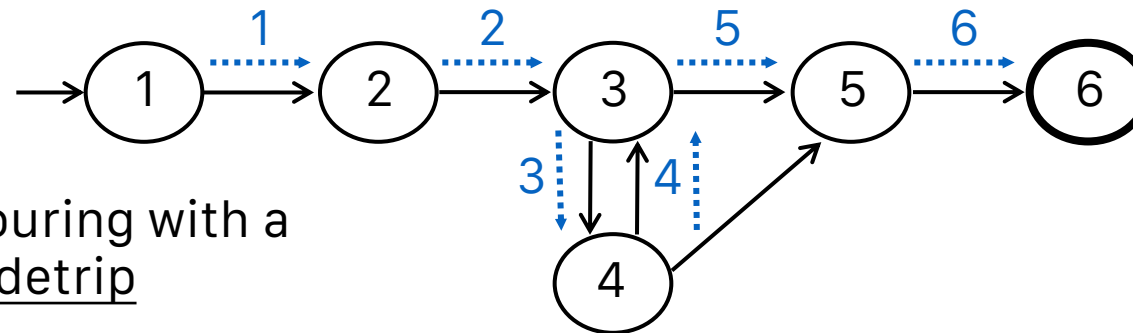
**Tour with detours:** *A test path  $p$  tours subpath  $q$  with detours iff every node in  $q$  is also in  $p$  in the same order*

- The tour can include a detour from node  $n_i$ , as long as it comes back to the prime path at a successor of  $n_i$

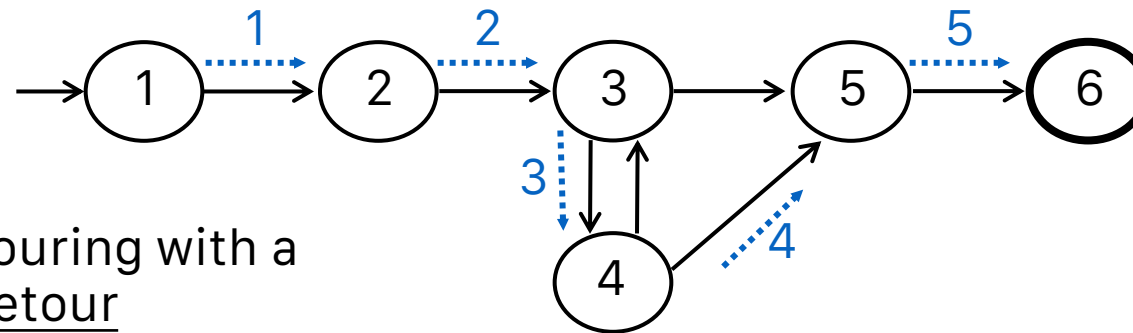
# Sidetrrips and Detours Example



Touring the prime path  
[1, 2, 3, 5, 6] without  
sidetrrips or detours



Touring with a  
sidetrip



Touring with a  
detour

# Infeasible Test Requirements

An **infeasible** test requirement cannot be satisfied.

- Unreachable statement (dead code)
- Subpath that can only be executed with a contradiction ( $x > 0$  and  $x < 0$ )

Most test **criteria** have some infeasible test requirements

It is usually **undecidable** whether all test requirements are feasible

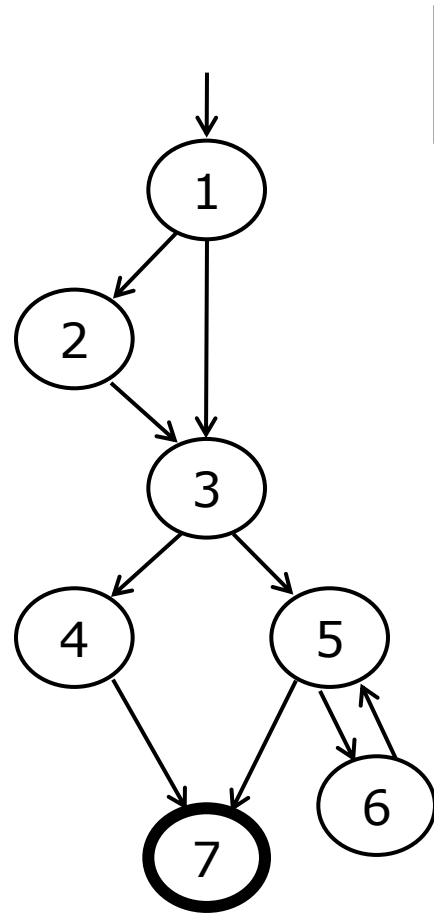
When sidetrips are not allowed, many structural criteria have **more infeasible test requirements**

However, always allowing **sidetrips weakens** the test criteria

Practical recommendation—Best Effort Touring

- Satisfy as many test requirements as possible without sidetrips
- Allow sidetrips to try to satisfy remaining test requirements

# Simple & Prime Path Example



Simple paths

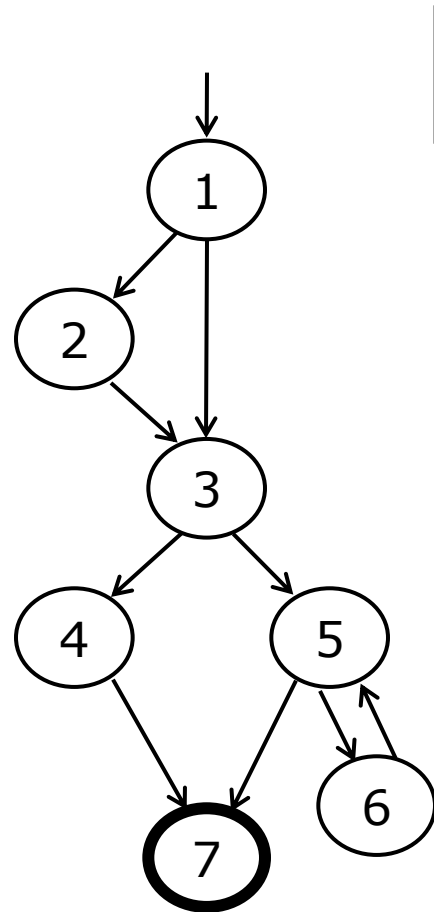
Write paths of length 0

Len 0  
[1]  
[2]  
[3]  
[4]  
[5]  
[6]  
[7] !

! means path terminates



# Simple & Prime Path Example

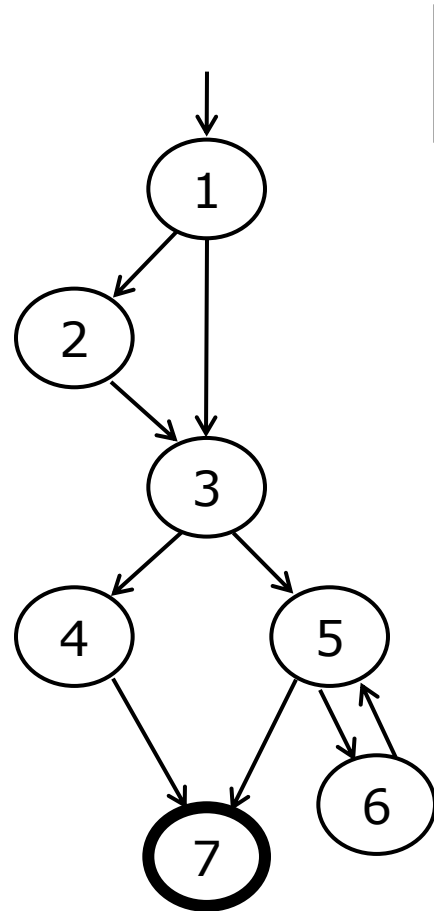


Simple paths

Write paths of length 1

Len 1  
[1, 2]  
[1, 3]  
[2, 3]  
[3, 4]  
[3, 5]  
[4, 7]!  
[5, 7]!  
[5, 6]  
[6, 5]

# Simple & Prime Path Example



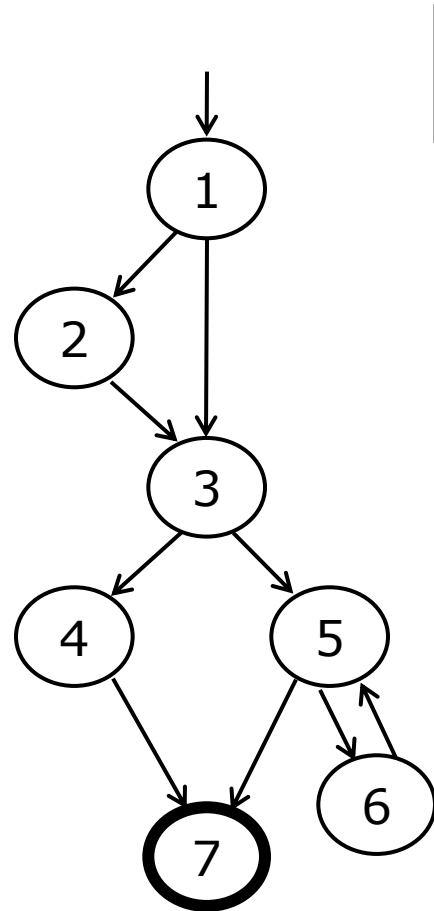
Simple paths

Write paths of length 2

- Len 2
- [1, 2, 3]
  - [1, 3, 4]
  - [1, 3, 5]
  - [2, 3, 4]
  - [2, 3, 5]
  - [3, 4, 7]!
  - [3, 5, 7]!
  - [3, 5, 6]!
  - [5, 6, 5] \*
  - [6, 5, 7]!
  - [6, 5, 6] \*

'\*' means path cycles

# Simple & Prime Path Example



Simple paths

Write paths of length 3

Len 3

[1, 2, 3, 4]

[1, 2, 3, 5]

[1, 3, 4, 7]!

[1, 3, 5, 7]!

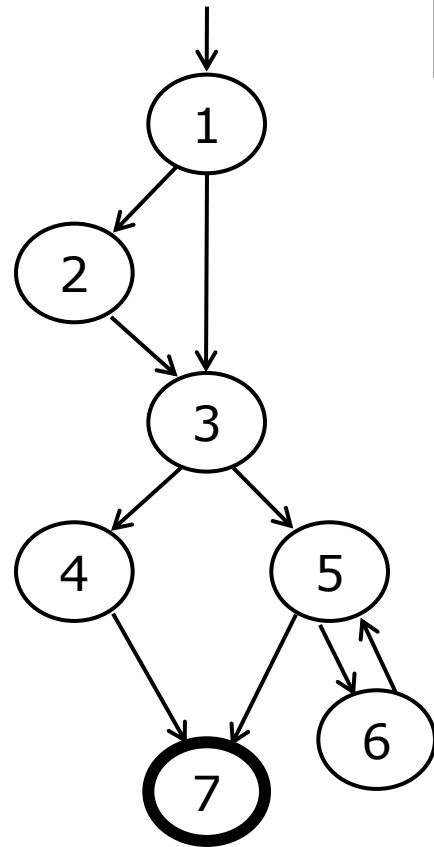
[1, 3, 5, 6]!

[2, 3, 4, 7]!

[2, 3, 5, 6]!

[2, 3, 5, 7]!

# Simple & Prime Path Example



Simple paths

Write paths of length 4

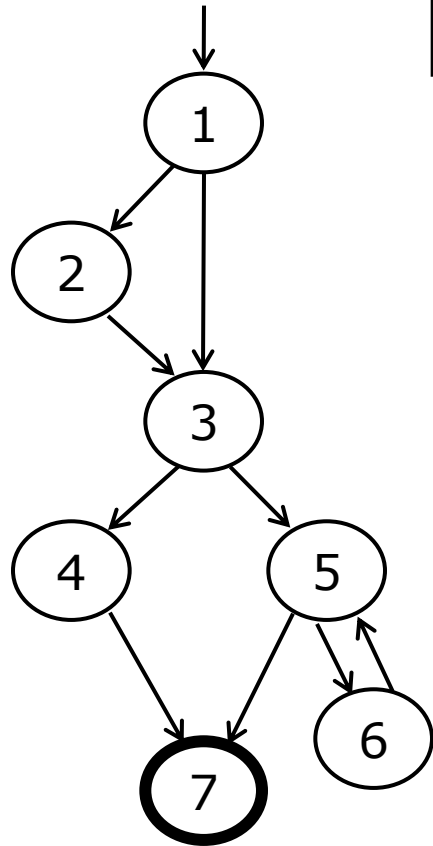
Len 4

[1, 2, 3, 4, 7]!

[1, 2, 3, 5, 7]!

[1, 2, 3, 5, 6]!

# Simple & Prime Path Example



Simple paths

Len 0  
 [1]  
 [2]  
 [3]  
 [4]  
 [5]  
 [6]  
 [7]!

Len 1  
 [1, 2]  
 [1, 3]  
 [2, 3]  
 [3, 4]  
 [3, 5]  
 [4, 7]!  
 [5, 7]!  
 [5, 6]  
 [6, 5]

Len 2  
 [1, 2, 3]  
 [1, 3, 4]  
 [1, 3, 5]  
 [2, 3, 4]  
 [2, 3, 5]  
 [3, 4, 7]!  
 [3, 5, 7]!  
 [3, 5, 6]!  
 [5, 6, 5]\*  
 [6, 5, 7]!  
 [6, 5, 6]\*

Len 3  
 [1, 2, 3, 4]  
 [1, 2, 3, 5]  
 [1, 3, 4, 7]!  
 [1, 3, 5, 7]!  
 [1, 3, 5, 6]!  
 [2, 3, 4, 7]!  
 [2, 3, 5, 6]!  
 [2, 3, 5, 7]!

**Prime Paths ?**

Len 4  
 [1, 2, 3, 4, 7]!  
 [1, 2, 3, 5, 7]!  
 [1, 2, 3, 5, 6]!

# Round Trips

**Round-Trip Path:** *A prime path that starts and ends at the same node*

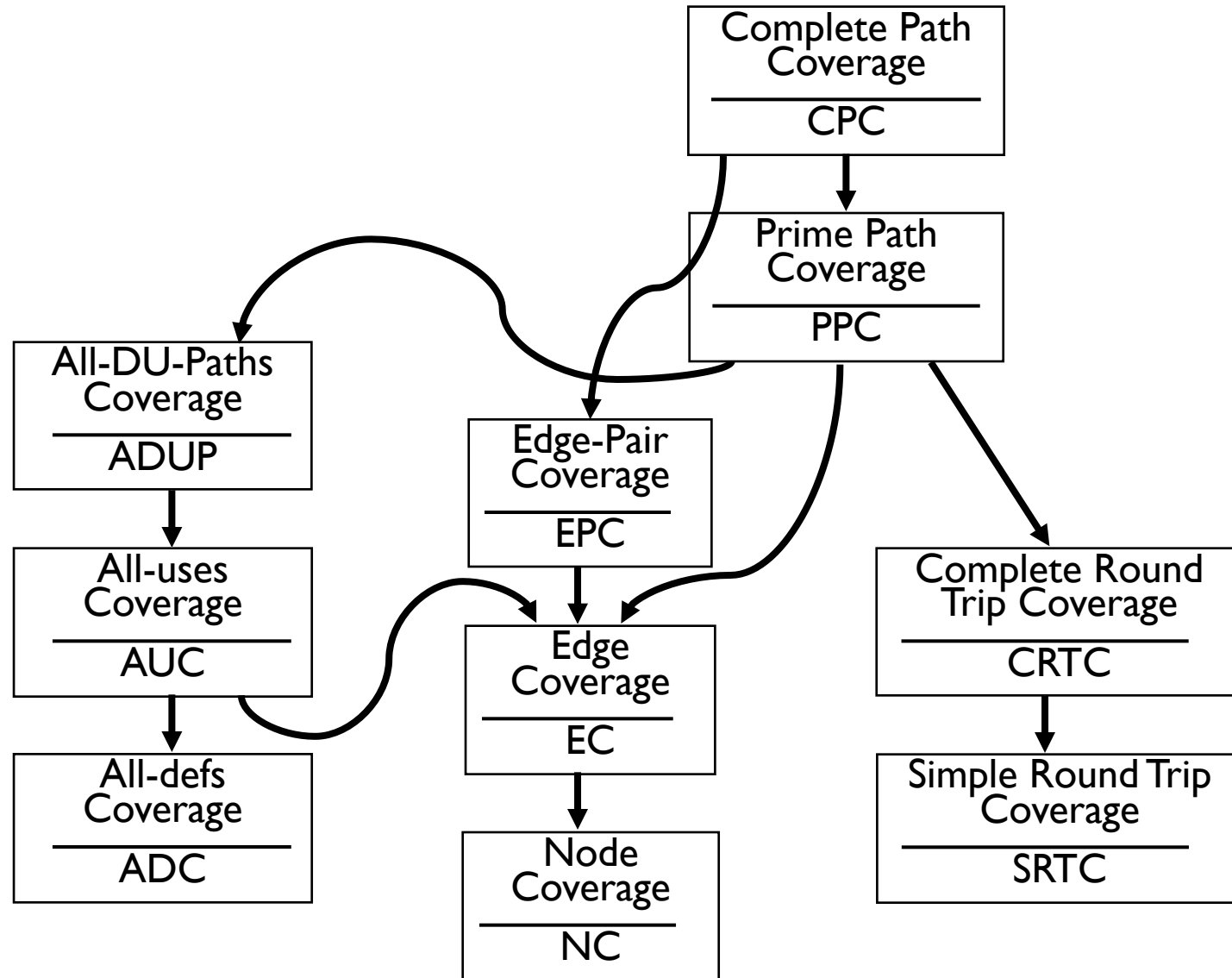
**Simple Round Trip Coverage (SRTC): TR contains at least one round-trip path for each reachable node in  $G$  that begins and ends a round-trip path.**

**Complete Round Trip Coverage (SRTC): TR contains all round-trip paths for each reachable node in  $G$ .**

These criteria **omit nodes and edges** that are not in round trips

Thus they do **not subsume** edge-pair, edge, or node coverage

# Graph Coverage Criteria Subsumption



# Summary 7.1-7.2

Graphs are a very **powerful abstraction** for designing tests

The various criteria allow lots of **cost/benefit** tradeoffs

These two sections are entirely at the "**design abstraction level**" from chapter 2

Graphs appear in **many situations** in software

- As discussed in the rest of chapter 7